

# CosyVerif: An Open Source Extensible Verification Environment

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## Motivation



#### Many tools for distributed systems verification

- Relying on different formalisms
- Solving different problems
- Running on different OS
- Requiring some difficult installation procedures
- $\rightsquigarrow$  Needs for:
  - A unified representation
  - Interoperability and tool integration
  - For users: Easy installation and use
  - For developers: Easy integration of tools



## Outline



## The CosyVerif Environment

Integrated Tools

#### 3 Summary and Evolutions



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# A Common and Reusable Syntax



- Cosy Verif relies on reusable and extensible formalisms [André et al., 2013]
- FML (Formalism Markup Language)
  - Describes formalisms (meta-models)
- GrML (Graph Markup Language)
  - Describes models
- Advantages
  - Unified model representation
  - Easy addition of new formalisms
- Applications: set of formalisms
  - Large family of (timed) automata and Petri nets



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• Easy to install: simple and light multi-platform client connecting to servers



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• Tool invocation through Web services transparent to the end-user



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Numerous tools integrated to CosyVerif

- One official client: Coloane (platform-independent)
- 6 tools and 9 integrated services
  - ▶ Integration via Web services: easy to use and compose
- Multiple formalisms supported (Petri nets and extensions, hybrid automata, timed automata...and more!)



## Statistical model checker [Ballarini et al., 2011]



- Input: Generalised Stochastic Petri Nets with general distribution (GSPN) and a Hybrid Automaton Stochastic Logic (HASL) formula
- Output: Statistical estimation of the formula with a confidence interval



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## State space generation & CTL verification [Colange et al., 2011]

- Symbolic/symbolic approach based on Symmetric Nets with Bags [Haddad et al., 2009]
- Two symbolic techniques to counter state space explosion
  - symmetries to reduce the reachability graph [Chiola et al., 1991]
     hierarchical Set Decision Diagrams to store the reachability graph [Couvreur and Thierry-Mieg, 2005]

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## Unfolding-based verification of Petri nets with read arcs (contextual nets) [Baldan et al., 2012]

### Features

- ▶ Unfolding construction tool [Rodríguez et al., 2011]
- Reachability and deadlock checking tool [Rodríguez and Schwoon, 2012]

## Characteristics

- Unfoldings fully represent the state space of a c-net by a partial order rather than by a set of interleavings
  - $\star\,$  Often exponentially smaller than the state space, and never larger
- c-net unfoldings can be exponentially more compact than those of corresponding Petri nets [Baldan et al., 2012]





## Parameter synthesis for real-time systems [André et al., 2012]

#### • Quantitative robustness analysis

- "Can we increase some of the timing delays such that the system still behaves well?"
- Schedulability analysis
- Hybrid system verification









## Construction and analysis of modular state spaces

[Lakos and Petrucci, 2004]

#### • Modular State Spaces for Synchronised Automata

- synchronisation structure
- only reachable parts of the automata

#### Analysis

- forward and backward reachability
- deadlock-checking
- liveness







# State space generation and CTL formulæ evaluation on P/T nets [Hong et al., 2012]

- Handles Symmetric Nets through their unfolding into an equivalent P/T net
- Exploits hierarchy: a state is seen as a tree, where the leaves correspond to place markings
- Relies on Set Decision Diagrams [Couvreur and Thierry-Mieg, 2005]



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# An Open Environment

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#### • Entirely open source

#### • Open to contributions

- Tool integration
- Alternative clients
- New formalisms

#### • A repository of models using a common syntax

 Coming from the integrated tools, and the model checking contests [Kordon et al., 2013]



# Recent and Ongoing Evolutions

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#### • Asynchronous tool invocation

▶ Get the result later (e.g., by email)

#### • Federation of servers and use of clusters

- Enable load balancing
- Repository of formalisms and models
- Command-line version of the underlying platform



# Future Evolutions

• Enhanced interaction between tools



- Output of a tool as input of another one
- Handling semantics (bridges between formalisms)
  - Also allows system simulation
- Handling heterogeneous models (mixing different formalisms)



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Try it!

## http://cosyverif.org/



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