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A Benchmarks Library for Extended Parametric Timed Automata

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Motivation

- ▶ Real-time systems:
 - ▶ Systems for which not only the functional correctness but also the time answer is important

Motivation

- ▶ **Critical Real-time systems:**
 - ▶ Systems for which not only the functional correctness but also the time answer is important
 - ▶ Failures (in correctness or timing) may result in dramatic consequences

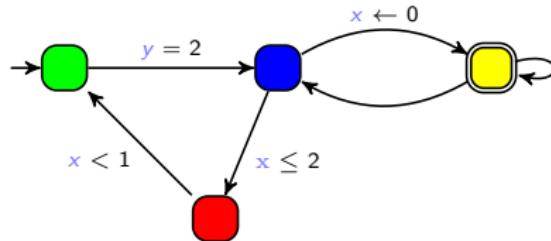


Outline

Parametric timed model checking

Our new benchmarks library

Timed model checking

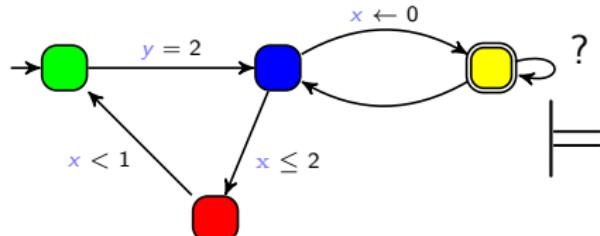


A **model** of the system

is unreachable

A **property** to be satisfied

Timed model checking



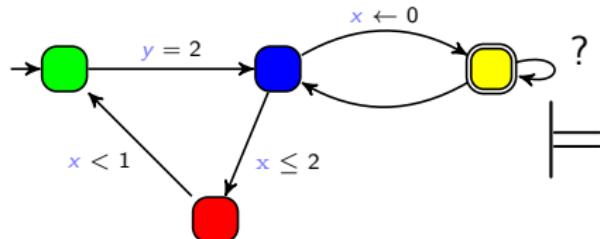
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- ▶ Question: does the model of the system satisfy the property?

Timed model checking



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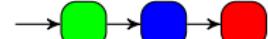
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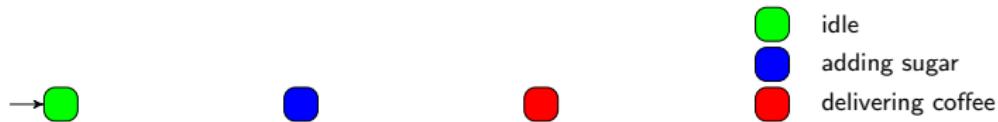
No



Counterexample

Timed automaton (TA)

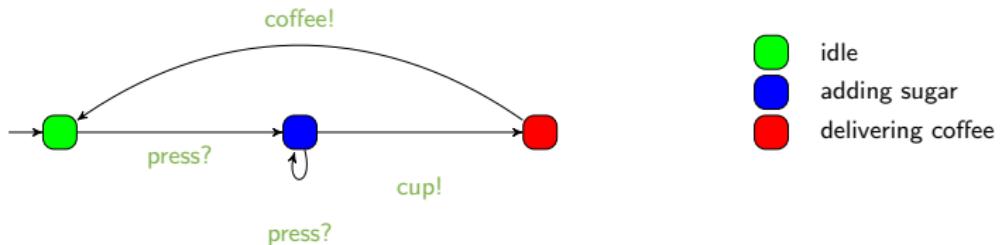
- ▶ Finite state automaton (sets of locations)



[AD94] Rajeev Alur and David L. Dill. "A theory of timed automata". In: *Theoretical Computer Science* 126.2 (Apr. 1994), pp. 183–235. ISSN: 0304-3975

Timed automaton (TA)

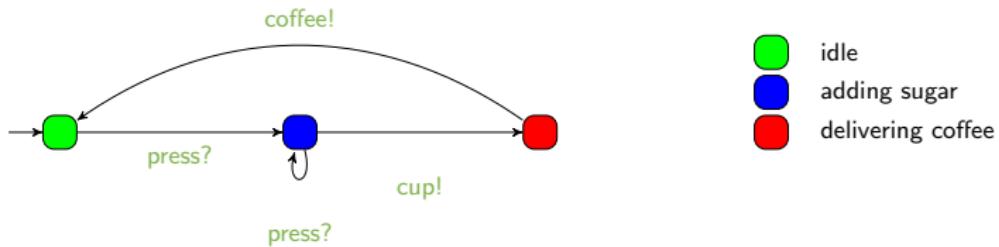
- Finite state automaton (sets of locations and actions)



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Timed automaton (TA)

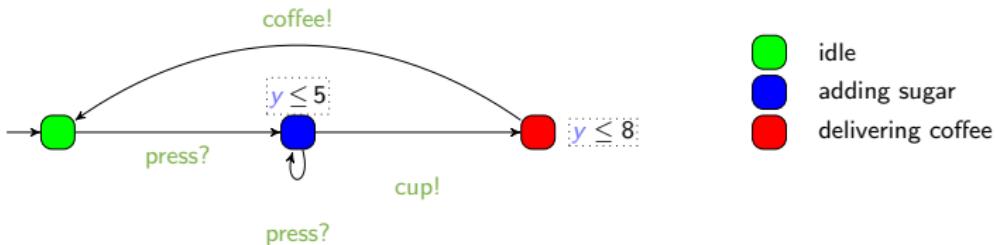
- ▶ Finite state automaton (sets of locations and actions) augmented with a set X of clocks [AD94]
 - ▶ Real-valued variables evolving linearly at the same rate
 - ▶ Can be compared to integer constants



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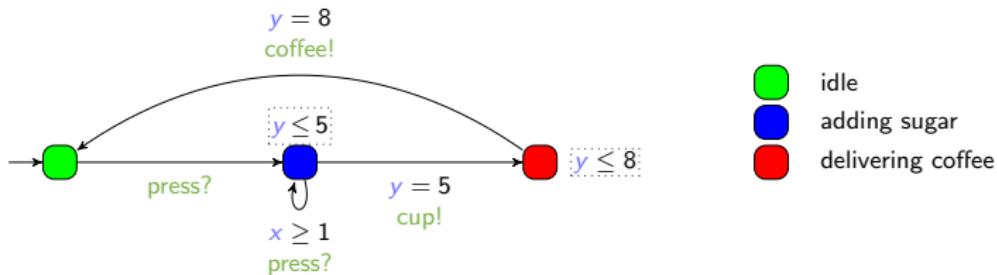
- ▶ Finite state automaton (sets of **locations** and **actions**) augmented with a set X of **clocks** [AD94]
 - ▶ Real-valued variables evolving linearly **at the same rate**
 - ▶ Can be compared to integer constants in invariants
- ▶ Features
 - ▶ Location **invariant**: property to be verified to stay at a location



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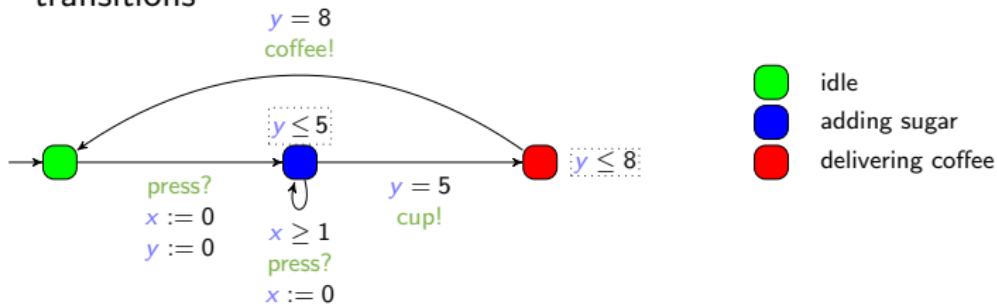
- ▶ Finite state automaton (sets of **locations** and **actions**) augmented with a set X of **clocks** [AD94]
 - ▶ Real-valued variables evolving linearly **at the same rate**
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- ▶ Features
 - ▶ Location **invariant**: property to be verified to stay at a location
 - ▶ Transition **guard**: property to be verified to enable a transition



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 - ▶ Location **invariant**: property to be verified to stay at a location
 - ▶ Transition **guard**: property to be verified to enable a transition
 - ▶ Clock **reset**: some of the clocks can be **set to 0** along transitions



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Timed automata: a useful formalism for verification and testing

- ▶ Timed automata are a common formalism to reason about systems involving timing and concurrency
- ▶ Nice decidability results [AD94]
- ▶ Many interesting applications
 - ▶ Notably testing [Lut+17] and monitoring [AHW18]

[AD94] Rajeev Alur and David L. Dill. "A theory of timed automata". In: *Theoretical Computer Science* 126.2 (Apr. 1994), pp. 183–235. ISSN: 0304-3975

[Lut+17] Lars Lüthmann et al. "Modeling and Testing Product Lines with Unbounded Parametric Real-Time Constraints". In: *SPLC, Volume A*. ACM, 2017, pp. 104–113

[AHW18] Étienne André, Ichiro Hasuo, and Masaki Waga. "Offline timed pattern matching under uncertainty". In: *ICECCS*. IEEE Computer Society, 2018, pp. 10–20

Beyond timed model checking: parameter synthesis

- ▶ Verification for **one** set of constants does not usually guarantee the correctness for other values
- ▶ Challenges
 - ▶ **Numerous verifications**: is the system correct for any value within [40; 60]?
 - ▶ **Optimization**: until what value can we increase a given constant while preserving correctness?
 - ▶ **Robustness** [BMS13]: What happens if 50 is implemented with 49.99?
 - ▶ **System incompletely specified**: Can I verify my system even if I don't know the period value with full certainty?

[BMS13] Patricia Bouyer, Nicolas Markey, and Ocan Sankur. "Robustness in timed automata". In: *RP*. vol. 8169. Lecture Notes in Computer Science. Invited paper. Springer, Sept. 2013, pp. 1–18

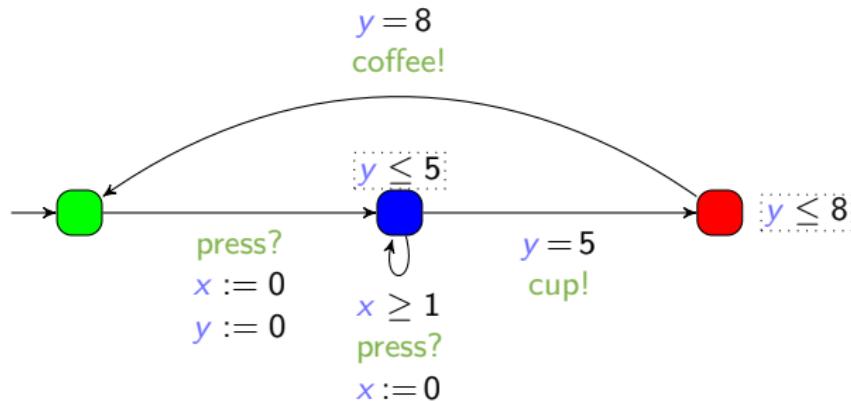
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 - ▶ **System incompletely specified**: Can I verify my system even if I don't know the period value with full certainty?
- ▶ **Parameter synthesis**
 - ▶ Consider that timing constants are unknown constants (**parameters**)

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Parametric Timed Automaton (PTA)

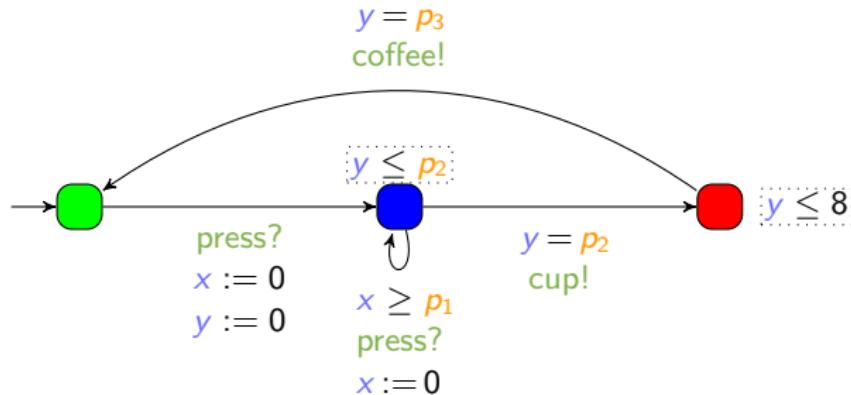
- ▶ Timed automaton (sets of locations, actions and clocks)



[AHV93] Rajeev Alur, Thomas A. Henzinger, and Moshe Y. Vardi. “Parametric real-time reasoning”. In: STOC. ACM, 1993, pp. 592–601. ISBN: 0-89791-591-7

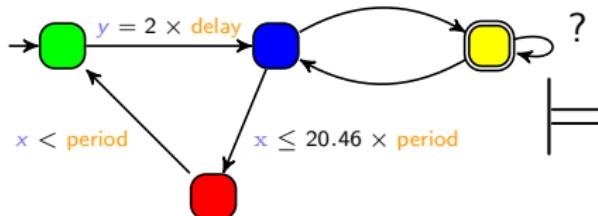
Parametric Timed Automaton (PTA)

- ▶ Timed automaton (sets of **locations**, **actions** and **clocks**) augmented with a set P of **parameters** [AHV93]
- ▶ Unknown rational constants compared to a **clock** in guards and invariants



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timed model checking



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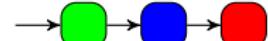
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- ▶ Question: does the model of the system satisfy the property?

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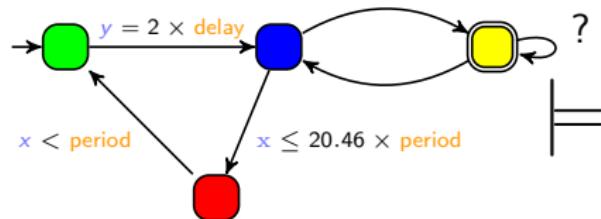


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Counterexample

Parametric timed model checking



A **model** of the system

is unreachable

A **property** to be satisfied

- ▶ Question: **for what values of the parameters** does the model of the system **satisfy** the property?

Yes if...

$$2 \times \text{delay} > 20.46 \times \text{period}$$



An undecidable formalism

- ▶ Parametric timed automata are very expressive
 - ▶ Most interesting problems are undecidable [AHV93]
 - ▶ Exact parameter synthesis is **out of reach**
 - ▶ ... but approximated algorithms, or exact algorithms without guarantee of termination, can be proposed
 - ▶ In practice: many interesting problems can still be solved (exactly)

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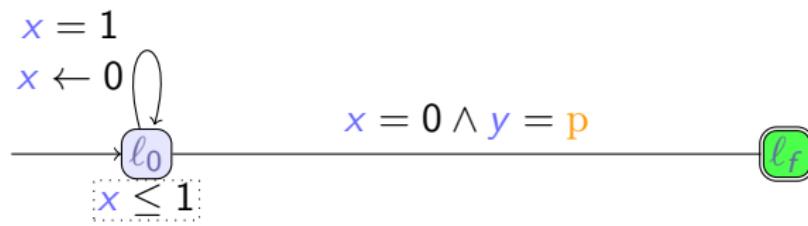
Our new benchmarks library

Motivation

- ▶ **Test** new algorithms for TAs or PTAs and check their efficiency by comparing them with existing techniques
- ▶ **Improve** existing techniques and tools
- ▶ Provide a set of “unsolvable” (yet very simple) benchmarks:
 - ▶ **Emphasize the limits** of state-of-the-art algorithms to encourage the community to address these cases

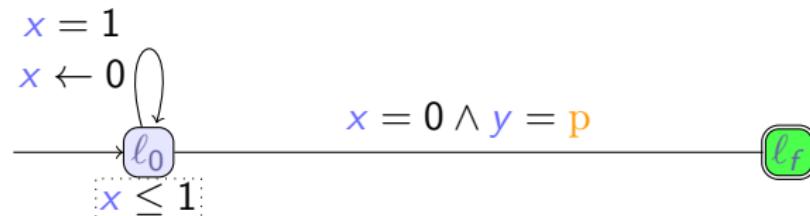
Motivation

Example of an “unsolvable” model



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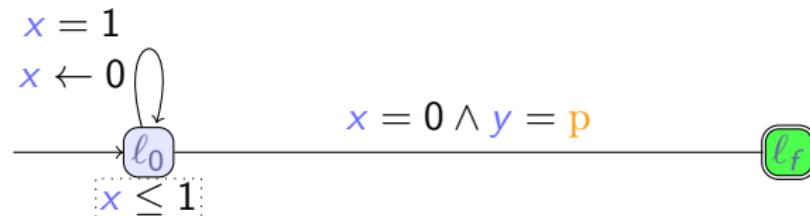


ℓ_f is reachable iff $p \in \mathbb{N}$

$p = 1$:

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Example of an “unsolvable” model



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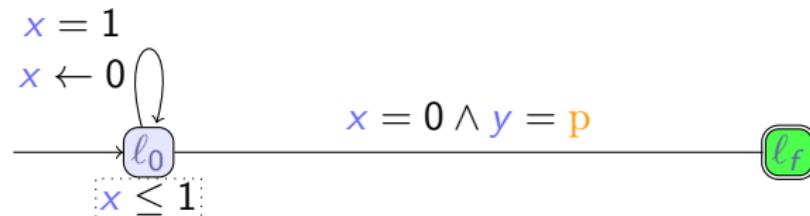
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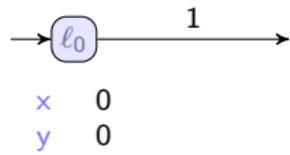
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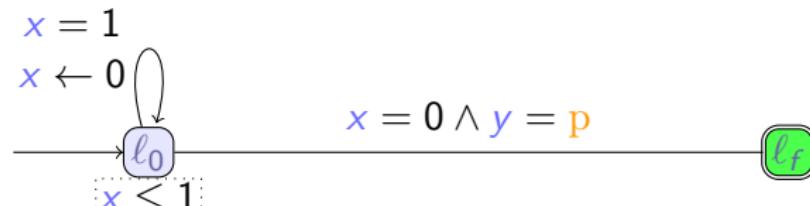
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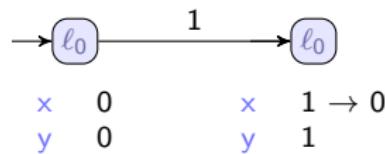
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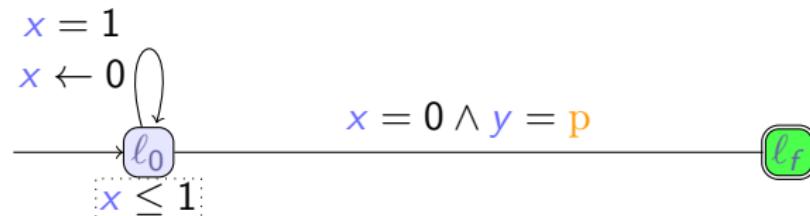
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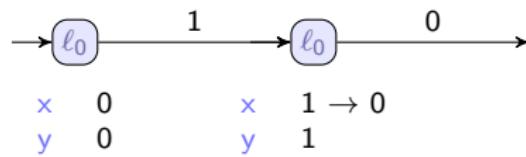
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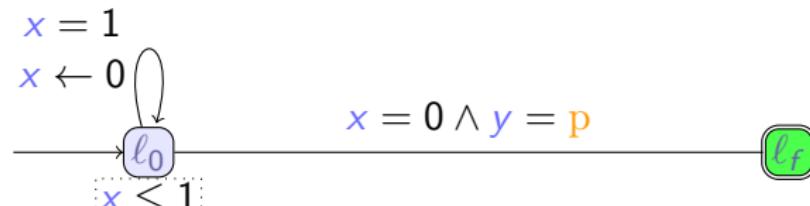
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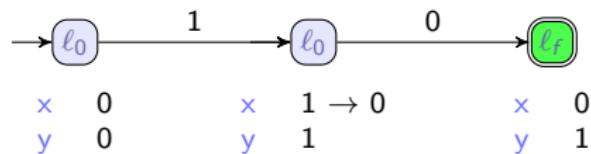
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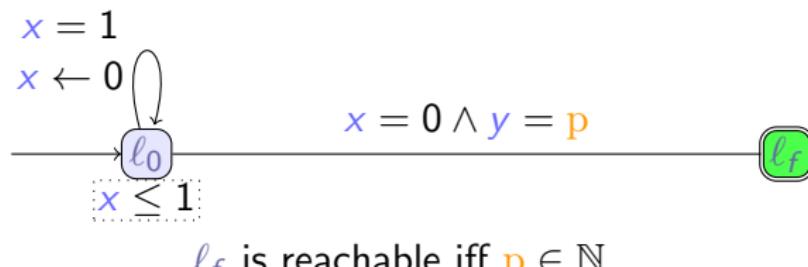
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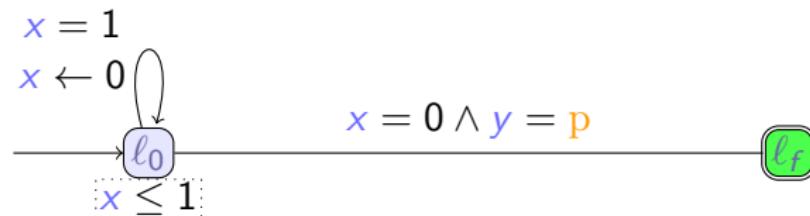
Example of an “unsolvable” model



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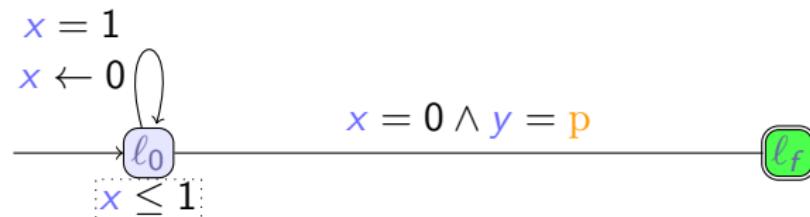
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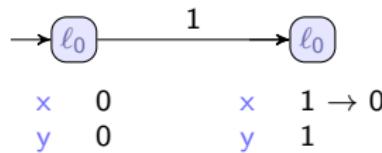
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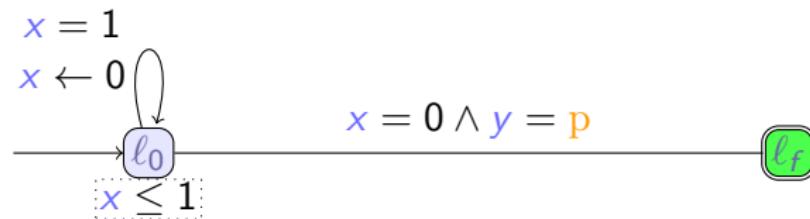
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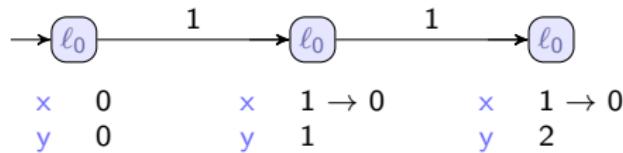
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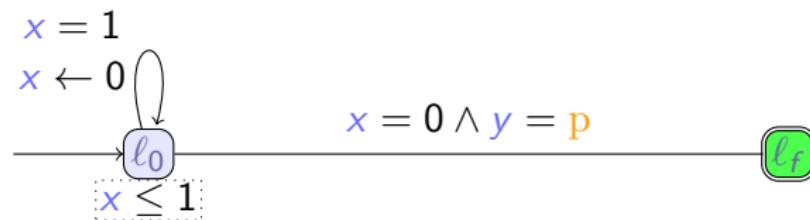
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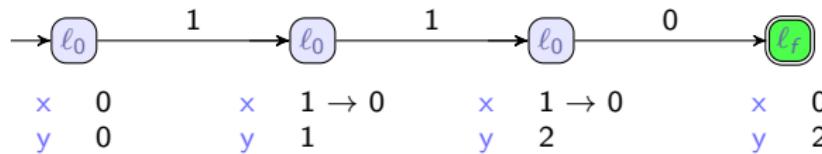
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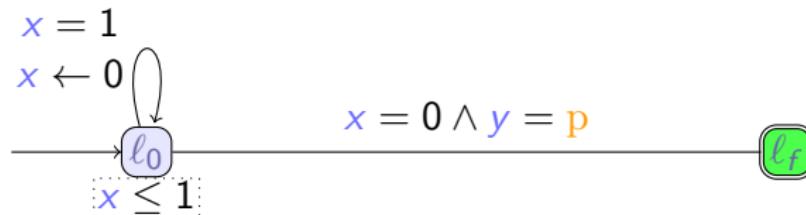
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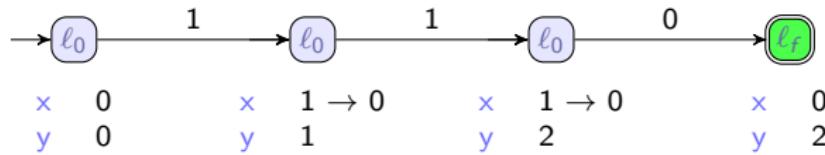
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Exact synthesis (i.e., inferring $p = i, i \in \mathbb{N}$) is not solvable by any existing parametric timed model checker (to the best of our knowledge)

Why a new version?

- ▶ A first library [And18] exists, but
 - ▶ the syntax is only compatible with the previous version of IMITATOR, and the former calling paradigm
 - ▶ it contains exclusively safety/reachability properties
 - ▶ only syntactic information is provided
 - ▶ No expected result

[And18] Étienne André. *The IMITATOR benchmarks library v1.0*. 2018. URL:
<https://www.imitator.fr/library1.html>

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 - ▶ only syntactic information is provided
 - ▶ No expected result
- ▶ New version:
 - ▶ More benchmarks
 - ▶ Focus on **liveness** properties
 - ▶ Focus on **unsolvable** benchmarks
 - ▶ Semantic information (computation time, expected result...)

[And18] Étienne André. *The IMITATOR benchmarks library v1.0*. 2018. URL:
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The IMITATOR library v2

| Library | Size | | | Metrics | | Properties | | |
|--------------|--------|--------|-------|---------|----------|------------|-----|----------|
| Vers. | Bench. | Models | Prop. | Static | Semantic | EF | TPS | liveness |
| 1.0 | 34 | 80 | 122 | ✓ | ✗ | ✓ | ✓ | ✗ |
| 2.0 [AMP21b] | 56 | 119 | 216 | ✓ | ✓ | ✓ | ✓ | ✓ |

| Library | Format | | | Categories | Analysis |
|---------|--------|------|----------|------------|----------|
| Vers. | .imi | Jani | [Bud+17] | Unsolvable | Results |
| 1.0 | 2.12 | | ✗ | ✗ | ✗ |
| 2.0 | 3.0 | | ✓ | ✓ | ✓ |

[AMP21b] Étienne André, Dylan Marinho, and Jaco van de Pol. *The IMITATOR benchmarks library v2.0*. 2021. URL: <https://www.imitator.fr/static/library2/>

[Bud+17] Carlos E. Budde et al. *JANI specification*. 2017. URL: <https://jani-spec.org/>

Origins and Provided formats

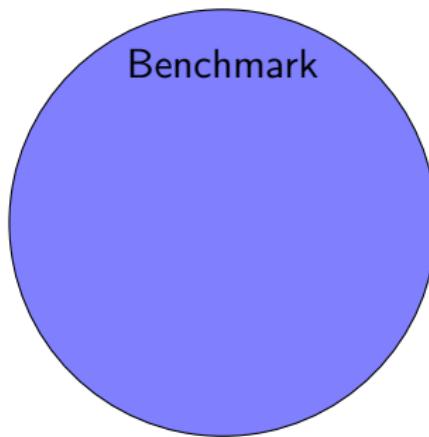
- ▶ Benchmarks come from industrial collaborations, from academic papers (from different communities), and from our experience in the field (toys, unsolvable)
- ▶ Two formats are provided:
 - ▶ The IMITATOR 3 syntax (.imi) [And21]
 - ▶ The JANIS Specification translation [Bud+17]
 - ▶ A new interchange format for automata-based formalisms

[And21] Étienne André. "IMITATOR 3: Synthesis of timing parameters beyond decidability". In: CAV. 2021
[Bud+17] Carlos E. Budde et al. *JANIS specification*. 2017. URL: <https://jani-spec.org/>

Tagging our models

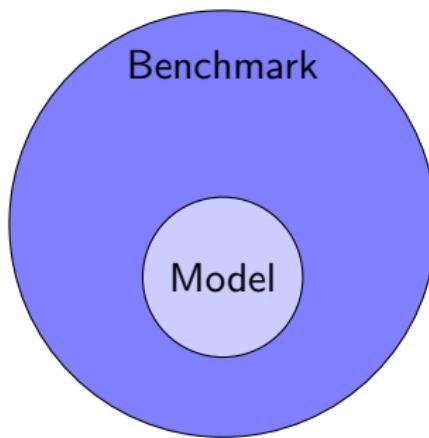
- ▶ All the benchmarks are tagged with one or more categories
- ▶ So far:
 - ▶ Academic,
 - ▶ Automotive,
 - ▶ Education,
 - ▶ Hardware,
 - ▶ Industrial,
 - ▶ Monitoring,
 - ▶ Producer-consumer,
 - ▶ Protocol,
 - ▶ Real-time system,
 - ▶ Scheduling,
 - ▶ Toy,
 - ▶ Unsolvable.

Structure of the library



Benchmark FischerPS08

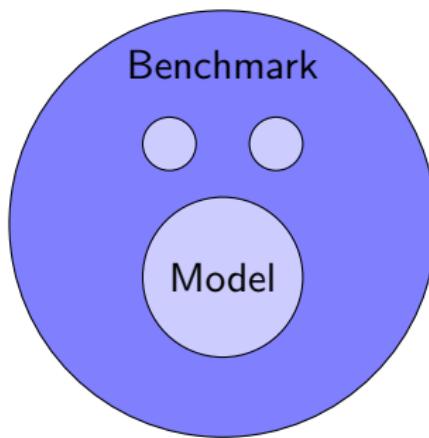
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Benchmark FischerPS08

Model FischerPS08:2

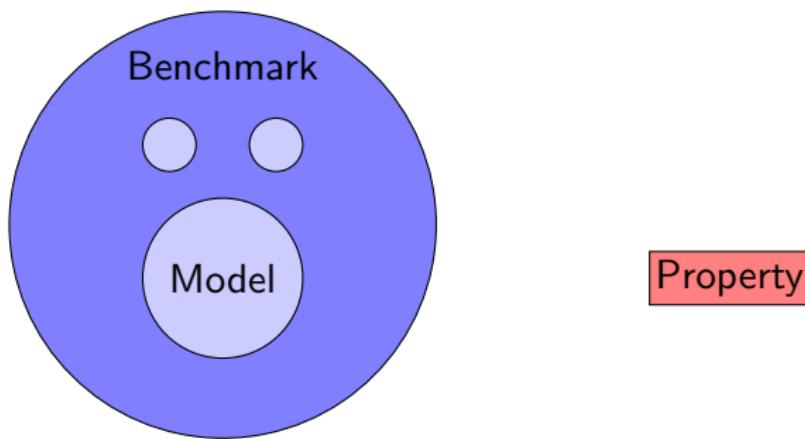
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Benchmark FischerPS08

Models FischerPS08:2, FischerPS08:3, ...

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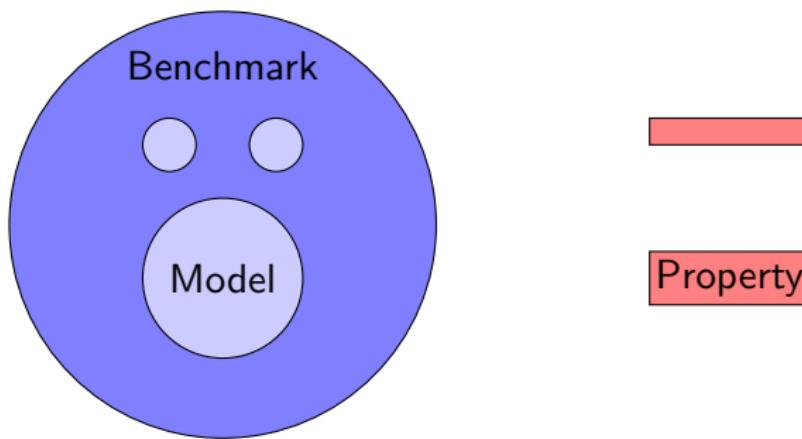


Benchmark FischerPS08

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Property FischerPS08:AGnot

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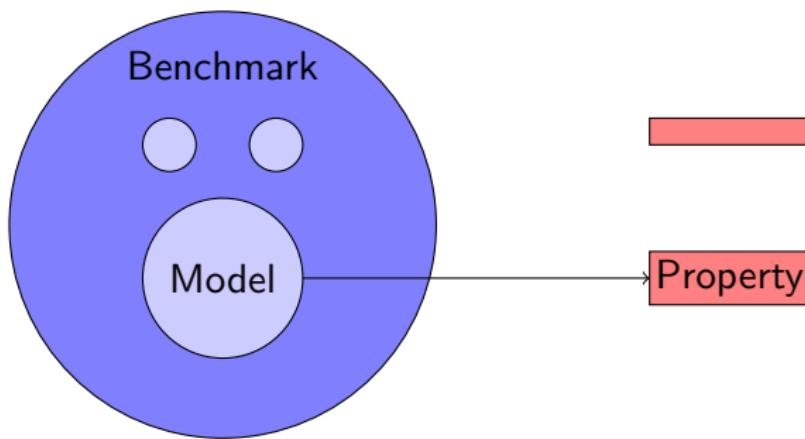


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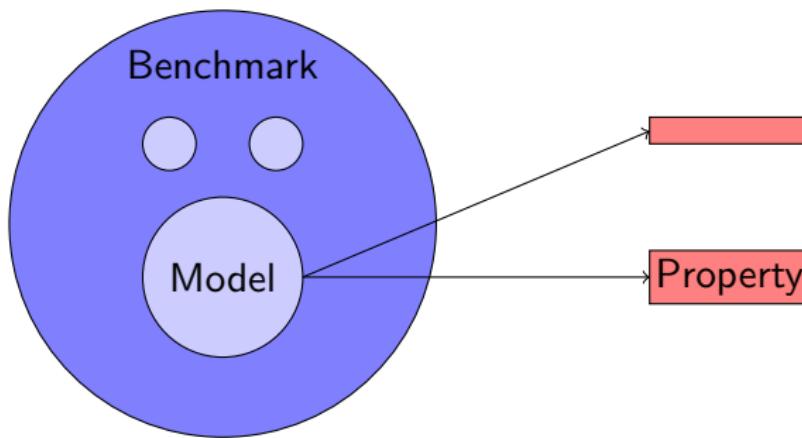


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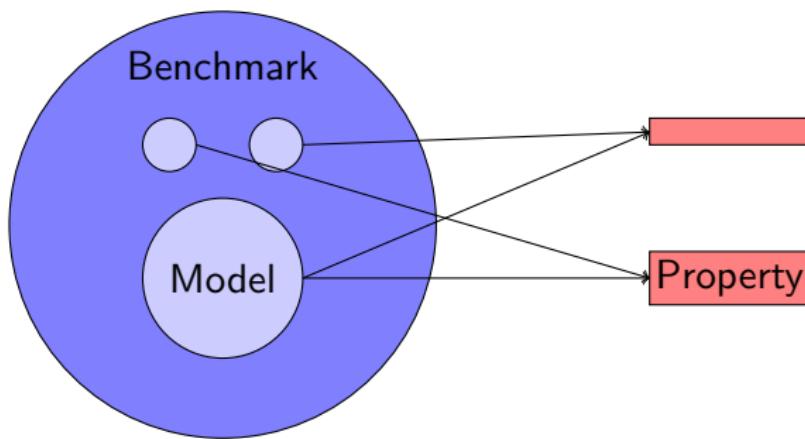


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How to select a subset of our benchmarks?

| Classification | Static | Semantic |
|-------------------|------------------|-------------------------|
| categorization | number of clocks | size of the state space |
| generation method | silent actions? | total computation time |
| scalability | ... | ... |

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For example

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Get all benchmarks

- ▶ that are scalable,
- ▶ that feature no invariant nor unobservable actions

How to select a subset of our benchmarks?

| Classification | Static | Semantic |
|-------------------|------------------|-------------------------|
| categorization | number of clocks | size of the state space |
| generation method | silent actions? | total computation time |
| scalability | ... | ... |

For example

Get all benchmarks

- ▶ that are scalable,
- ▶ that feature no invariant nor unobservable actions
- ▶ and for which the synthesis time is (approximately) between 10 and 60 seconds

Where to find it?

- ▶ Initial version DOI [AMP21a]
- ▶ A webpage (updated version) [AMP21b]

| Benchmark | File | Source | Categories | | | | | | | | | | | | Metrics | | | | | | | | | | | | Properties | | | | | | | |
|-----------|------------|--------|------------|-------|-------|-------|------|------|-------|-------|-----|-------|------|-------|---------|------|------|----|-------|------------|---------|------|-------|---|----------|-----|------------|---------|-------|---------|----------|----------|--------|--------|
| | | | Ac. | Auto. | Edits | Model | Ind. | Mac. | Prod. | Prov. | RFS | Sched | Star | Userd | Stat. | Cost | SPFA | SL | loc.1 | cyc. check | LAT | SLAT | SLAT2 | P | max. Var | Act | SL | avgSL | RI | avgV13 | Property | Name | Source | |
| accel | accel1000 | BB BB | IMITATOR | Auto. | | | Ind. | Mac. | | | | | | | yes | yes | 2 | 2 | true | false | not L/U | true | true | 3 | 0 | 11 | 2574 | 1287.8 | 2500 | 1256.8 | 2500 | 3.144 s | 4002 | 00008 |
| | accel2000 | BB BB | IMITATOR | Auto. | | | Ind. | Mac. | | | | | | | yes | yes | 2 | 2 | true | false | not L/U | true | true | 3 | 0 | 11 | 26152 | 12507.8 | 25176 | 12506.8 | 25176 | 2.275 s | 6504 | 00008 |
| | accel3000 | BB BB | IMITATOR | Auto. | | | Ind. | Mac. | | | | | | | yes | yes | 2 | 2 | true | false | not L/U | true | true | 3 | 0 | 11 | 26152 | 12507.8 | 25176 | 12506.8 | 25176 | 17.722 s | 63741 | 000709 |
| | accel4000 | BB BB | IMITATOR | Auto. | | | Ind. | Mac. | | | | | | | yes | yes | 2 | 2 | true | false | not L/U | true | true | 3 | 0 | 11 | 26152 | 12507.8 | 25176 | 12506.8 | 25176 | 15.003 s | 63773 | 000713 |
| | accel5000 | BB BB | IMITATOR | Auto. | | | Ind. | Mac. | | | | | | | yes | yes | 2 | 2 | true | false | not L/U | true | true | 3 | 0 | 11 | 26152 | 12507.8 | 25176 | 12506.8 | 25176 | 5.005 s | 12426 | 00008 |
| | accel7000 | BB BB | IMITATOR | Auto. | | | Ind. | Mac. | | | | | | | yes | yes | 2 | 2 | true | false | not L/U | true | true | 3 | 0 | 11 | 26152 | 12507.8 | 25176 | 12506.8 | 25176 | 3.109 s | 12475 | 00008 |
| | accel9000 | BB BB | IMITATOR | Auto. | | | Ind. | Mac. | | | | | | | yes | yes | 2 | 2 | true | false | not L/U | true | true | 3 | 0 | 11 | 26152 | 12507.8 | 25176 | 12506.8 | 25176 | 3.109 s | 12497 | 00008 |
| | accel10000 | BB BB | IMITATOR | Auto. | | | Ind. | Mac. | | | | | | | yes | yes | 2 | 2 | true | false | not L/U | true | true | 3 | 0 | 11 | 26152 | 12507.8 | 25176 | 12506.8 | 25176 | 3.109 s | 12497 | 00008 |

- ▶ with the static and semantic metrics
- ▶ with expected results (if exist)

[AMP21a] Étienne André, Dylan Marinho, and Jaco van de Pol. *The IMITATOR benchmarks library 2.0: A benchmarks library for extended parametric timed automata*. Apr. 2021. doi: 10.5281/zenodo.4730980

[AMP21b] Étienne André, Dylan Marinho, and Jaco van de Pol. *The IMITATOR benchmarks library v2.0*. 2021. URL: <https://www.imitator.fr/static/library2/>

Where to find it?

- ▶ Initial version DOI [AMP21a]
- ▶ A webpage (updated version) [AMP21b]

| Benchmark | File | Source | Categories | | | | | | | | | | Metrics | | | | | | | | | | Properties | | | | | | | | | | |
|-----------|------------|----------|------------|-------|-------|-------|------|------|-------|-------|-----|-------|---------|-----|-------|------|------|----|------|-----------|---------|------|------------|---|----------|-----|-------|---------|-------|---------|----------|------------|----------|
| | | | Ac. | Auto. | Edits | Model | Ind. | Min. | Prod. | Pres. | RFS | Sched | Star | UML | Stat. | Cams | SPFA | SL | Inv. | cyc check | LAT | SLAT | SLAT2 | P | max. Var | Act | SL | avg SL | RI | avg RI | Property | Name | Source |
| accel | accel_1000 | IMITATOR | Auto. | | | Ind. | Min. | | | | | | | | yes | yes | 2 | 2 | true | false | not L/U | true | true | 3 | 0 | 11 | 2574 | 1287.8 | 2500 | 1256.8 | IMITATOR | accel_1000 | IMITATOR |
| | accel_2000 | IMITATOR | Auto. | | | Ind. | Min. | | | | | | | | yes | yes | 2 | 2 | true | false | not L/U | true | true | 3 | 0 | 11 | 26152 | 12076.8 | 25176 | 12564.8 | IMITATOR | accel_2000 | IMITATOR |
| | accel_3000 | IMITATOR | Auto. | | | Ind. | Min. | | | | | | | | yes | yes | 2 | 2 | true | false | not L/U | true | true | 3 | 0 | 11 | 26152 | 12076.8 | 25176 | 12564.8 | IMITATOR | accel_3000 | IMITATOR |
| | accel_4000 | IMITATOR | Auto. | | | Ind. | Min. | | | | | | | | yes | yes | 2 | 2 | true | false | not L/U | true | true | 3 | 0 | 11 | 4099 | 2404.8 | 4077 | 2401.8 | IMITATOR | accel_4000 | IMITATOR |
| | accel_5000 | IMITATOR | Auto. | | | Ind. | Min. | | | | | | | | yes | yes | 2 | 2 | true | false | not L/U | true | true | 3 | 0 | 11 | 7014 | 3907.8 | 7032 | 3916.8 | IMITATOR | accel_5000 | IMITATOR |
| | accel_6000 | IMITATOR | Auto. | | | Ind. | Min. | | | | | | | | yes | yes | 2 | 2 | true | false | not L/U | true | true | 3 | 0 | 11 | 10960 | 5030.8 | 10070 | 5019.8 | IMITATOR | accel_6000 | IMITATOR |
| | accel_7000 | IMITATOR | Auto. | | | Ind. | Min. | | | | | | | | yes | yes | 2 | 2 | true | false | not L/U | true | true | 3 | 0 | 11 | 12140 | 6077.8 | 12044 | 6020.8 | IMITATOR | accel_7000 | IMITATOR |
| | accel_8000 | IMITATOR | Auto. | | | Ind. | Min. | | | | | | | | yes | yes | 2 | 2 | true | false | not L/U | true | true | 3 | 0 | 11 | 15290 | 7095.8 | 15408 | 7094.8 | IMITATOR | accel_8000 | IMITATOR |

- ▶ with the static and semantic metrics
- ▶ with expected results (if exist)

We are open to new model submissions!

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[AMP21b] Étienne André, Dylan Marinho, and Jaco van de Pol. *The IMITATOR benchmarks library v2.0*. 2021. URL: <https://www.imitator.fr/static/library2/>

Future work

- ▶ Keep enlarging the library using future benchmarks, and future synthesis algorithms
 - ▶ Add “difficulty” score to benchmarks (from easy to unsolvable)
- ▶ Bindings with other libraries, e. g.,
 - ▶ share a non-parametric version of PTAs to TAs libraries
 - ▶ integrate benchmarks from hybrid automata libraries to ours when the expressiveness is compatible
- ▶ Develop translations to other model checkers: e. g.,
 - ▶ Uppaal [LPY97] (non-parametric timed automata)
 - ▶ SpaceEx [Fre+11] (hybrid systems)
 - ▶ Roméo [Lim+09] (parametric time Petri nets)

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