

RP 2015

September 22nd, 2015

Warszawa

Integer-Complete Parameter Synthesis for Bounded Parametric Timed Automata

Étienne André^{1,2}, Didier Lime², Olivier H. Roux²

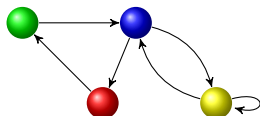
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²École Centrale de Nantes, IRCCyN, CNRS, UMR 6597, France



Context: Formal verification of timed systems

■ Model checking



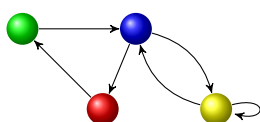
A **model** of the system

● is unreachable

A **property** to be satisfied

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?

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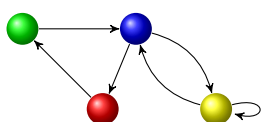
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- Question: does the model of the system **satisfy** the property?

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$$\models$$

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A **model** of the system

A **property** to be satisfied

■ Question: does the model of the system **satisfy** the property?

Yes



No



Counterexample

Beyond model checking: parameter synthesis

- Timed systems are characterized by a **set of timing constants**
 - “The packet transmission lasts for **50 ms**”
 - “The sensor reads the value every **10 s**”
- Verification for **one** set of constants does not usually guarantee the correctness for other values
- Challenges
 - **Numerous verifications**: is the system correct for any value within $[40; 60]$?
 - **Optimization**: until what value can we increase **10**?
 - **Robustness** [Markey, 2011]: What happens if **50** is implemented with **49.99**?

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 - **Robustness** [Markey, 2011]: What happens if **50** is implemented with **49.99**?
- **Parameter synthesis**
 - Consider that timing constants are unknown constants (**parameters**)
 - Find **good values** for the parameters

Outline

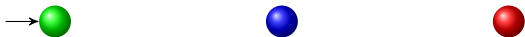
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- 2 Previous Works on Parameter Synthesis
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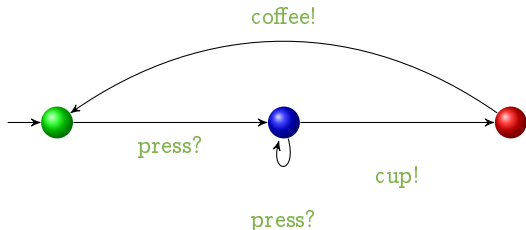
Timed automaton (TA)

- Finite state automaton (sets of **locations**)



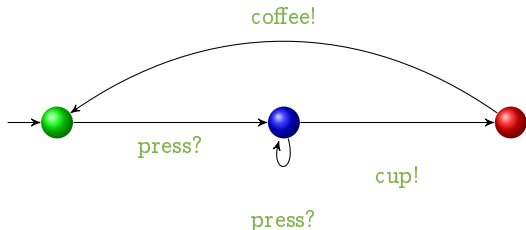
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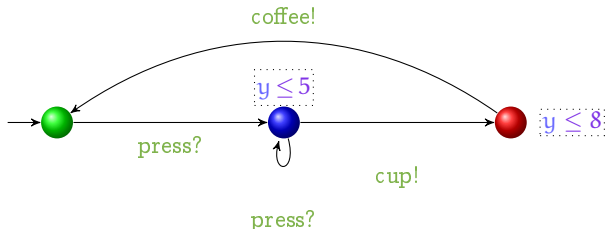
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 - Real-valued variables evolving linearly at the same rate



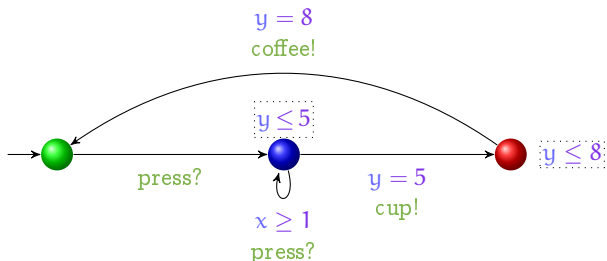
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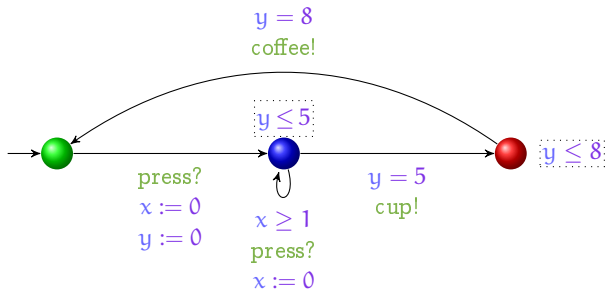
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 - Clock **reset**: some of the clocks can be set to 0 at each transition



Concrete semantics of timed automata

- **Concrete state** of a TA: pair (l, w) , where
 - l is a location,
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- **Concrete run**: alternating sequence of **concrete states** and **actions** or **elapsing of time**
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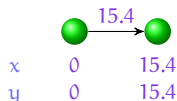


x	0
y	0

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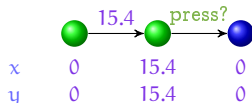
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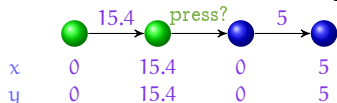


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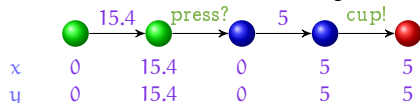
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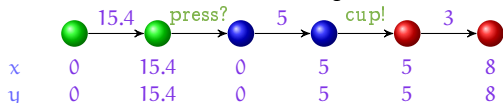
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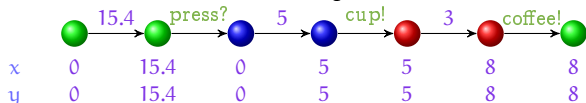
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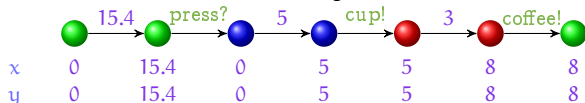
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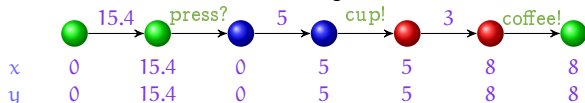
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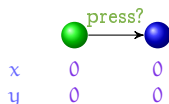
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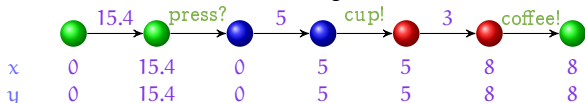
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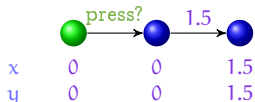
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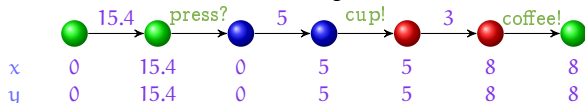
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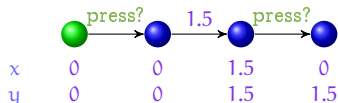
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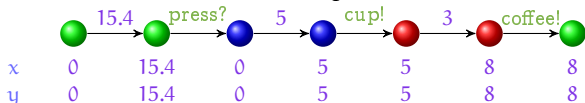
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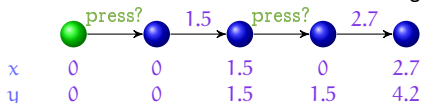
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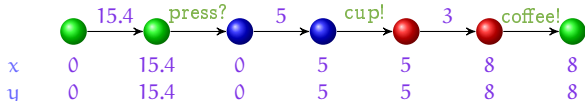
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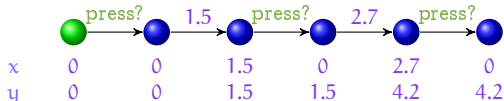
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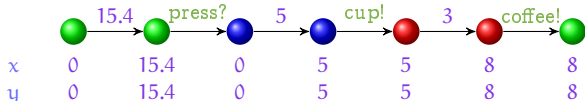
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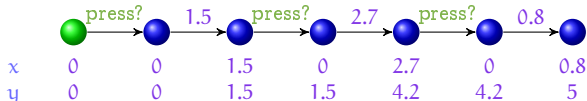
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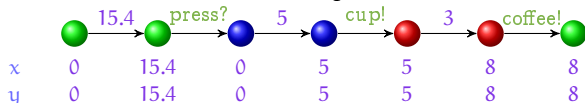
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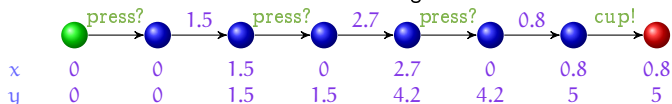
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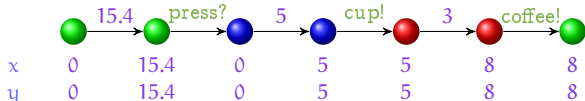
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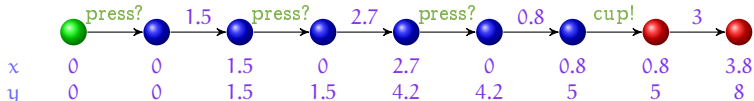
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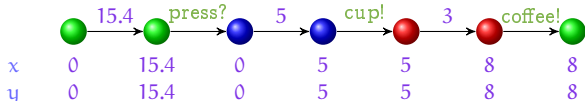
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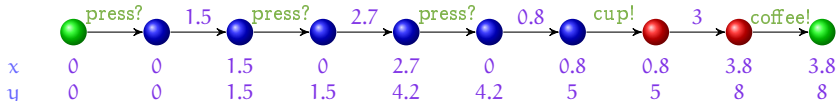
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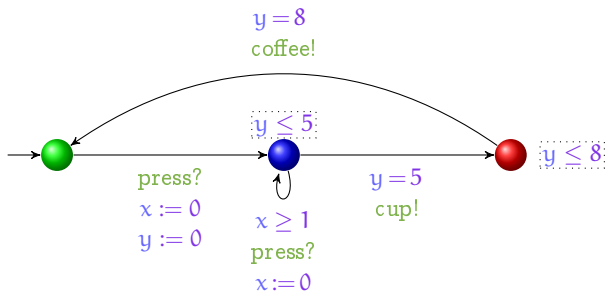


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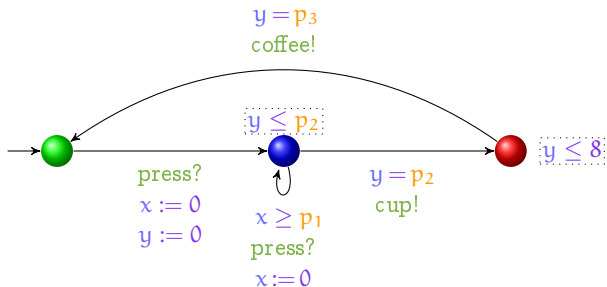
Parametric Timed Automaton (PTA)

- Timed automaton (sets of locations, actions and clocks)



Parametric Timed Automaton (PTA)

- Timed automaton (sets of locations, actions and clocks) augmented with a set P of parameters [Alur et al., 1993]
 - Unknown constants used in guards and invariants



Symbolic semantics of a PTA

- **Symbolic state** of a PTA: pair (l, C) , where
 - l is a location,
 - C is a **polyhedron** (conjunction of inequalities) over X and P

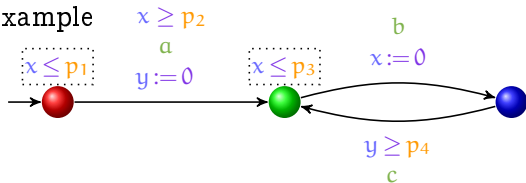
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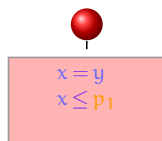
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- **Example**



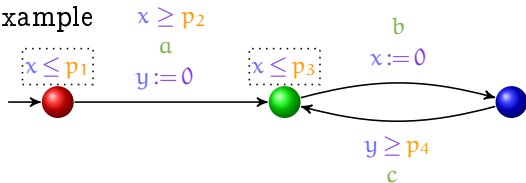
- Possible symbolic run for this PTA



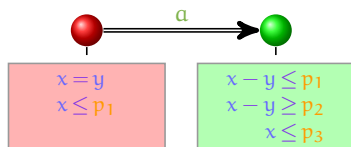
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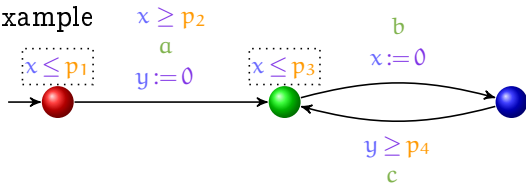
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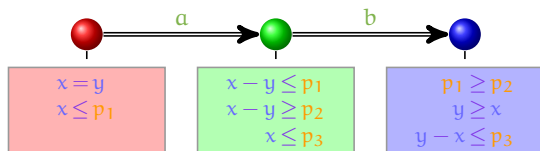
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- **Example**



- Possible symbolic run for this PTA



Valuation of a PTA

- Given a PTA \mathcal{A} and a parameter valuation ν , we denote by $\nu(\mathcal{A})$ the (non-parametric) timed automaton where all parameters are valuated by ν

Objective: Computation problems

Definition (reachability synthesis (EF))

Input: a PTA \mathcal{A} and a set of locations G

Problem: Synthesize all parameter valuations \mathbf{v} such that there exists a run of $\mathbf{v}(\mathcal{A})$ reaching a location $l \in G$

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Definition (unavoidability synthesis (AF))

Input: a PTA \mathcal{A} and a set of locations G

Problem: Synthesize all parameter valuations \mathbf{v} such that all runs of $\mathbf{v}(\mathcal{A})$ eventually reach a location $l \in G$

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Decidability results: reachability

Reachability emptiness

Reachability emptiness (“does there exist at least one parameter valuation reaching a given location l ?”) is **undecidable** for PTA

[Alur et al., 1993]

- even with a single parametric clock [Miller, 2000]
- even with only strict constraints [Doyen, 2007]
- even with a single integer-valued parameter [Beneš et al., 2015]

Decidability results: unavoidability

Reachability emptiness

Unavoidability emptiness (“does there exist at least one parameter valuation such that all runs reach a given location l ?”) is **undecidable** for PTA, even with a single bounded parameter

[Jovanović et al., 2015]

Synthesis of bounded integers

What if parameters are **bounded integers**...?

Synthesis of bounded integers

What if parameters are **bounded integers**...?

Bounded integers

Reachability and **unavoidability emptiness** are **decidable** (and PSPACE-complete) for PTA with bounded integers [[Jovanović et al., 2015](#)]

Synthesis of bounded integers

What if parameters are **bounded integers**...?

Bounded integers

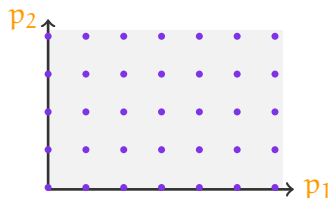
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Two algorithms:

- **IEF**: reachability synthesis
- **IAF**: unavoidability synthesis

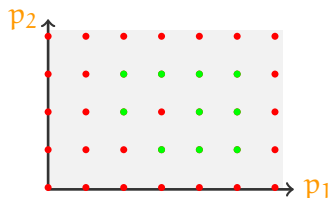
Synthesis of bounded integers: How?

Naive idea: enumerate all integers, and check the TA (which is PSPACE-complete [Alur and Dill, 1994])



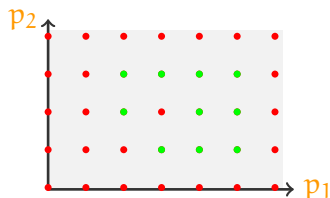
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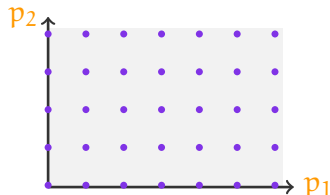
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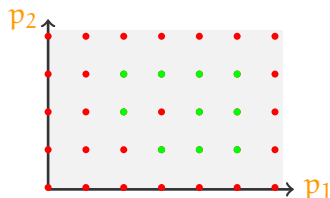
Smarter: **symbolic algorithm** [Jovanović et al., 2015]

- More efficient than exhaustive enumeration with UPPAAL



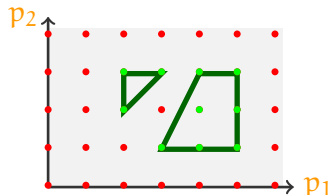
Synthesis of bounded integers: How?

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Integer hull of a polyhedron

Definition (integer hull)

Let C be a polyhedron.

The **integer hull** of C is

$$IH(C) = \text{Conv}(IV(C))$$

(**Conv**: convex hull; **IV** set of vectors with integer coordinates)

Integer hull of a polyhedron

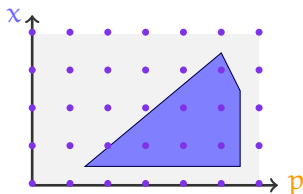
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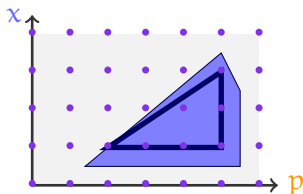
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Reachability synthesis

Algorithm $\text{EF}(\mathcal{A}, G)$

$K \leftarrow \perp$

Add the initial state to the waiting list

while the waiting list is not empty

 Pick a symbolic state (l, C) from the waiting list

 if $l \in G$ then $K \leftarrow K \vee (l, C) \downarrow_P$

 else if $(l, C) = (l', C')$, for some (l', C') met before

 then do not explore further this branch

 else store (l, C) and add its successors to the waiting list

return K

Reachability synthesis of bounded integers using IH

Algorithm $\text{IEF}(\mathcal{A}, G)$ [Jovanović et al., 2015]

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Add the initial state to the waiting list

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 Pick a symbolic state (l, C) from the waiting list

 if $l \in G$ then $K \leftarrow K \vee \text{IH}(C) \downarrow_P$

 else if $(l, \text{IH}(C)) = (l', \text{IH}(C'))$, for some (l', C') met before

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 else store $(l, \text{IH}(C))$ and add its successors to the waiting list

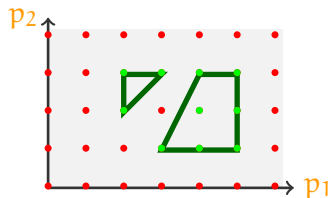
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Outline

- 1 Preliminaries
- 2 Previous Works on Parameter Synthesis
- 3 Integer-Complete Dense Synthesis**
- 4 Implementation in ROMÉO
- 5 Conclusion and Perspectives

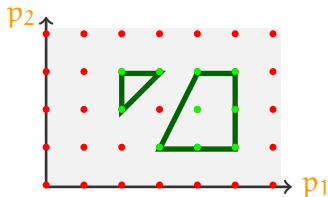
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IEF and IAF return **symbolic** sets of **integer** valuations



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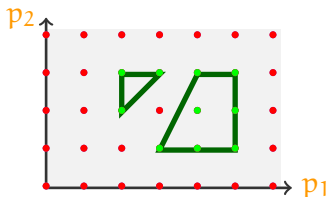
IEF and IAF return **symbolic** sets of **integer** valuations



Can we interpret the result of IEF and IAF over dense parameter valuations?

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IEF and IAF return **symbolic** sets of **integer** valuations



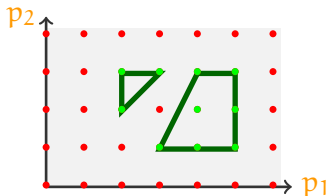
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(example in paper)

What about the dense result?

IEF and IAF return **symbolic** sets of **integer** valuations



Can we interpret the result of IEF and IAF over dense parameter valuations?

☹ For IEF: yes! ... but it **may not terminate**

(example in paper)

☹ For IAF: no! May yield **incorrect valuations**

(counter-example in paper)

A parametric extrapolation for PTA

Definition (M -extrapolation)

Let M be the largest constant in \mathcal{A} (including the bounds on the parameters), let x be a clock.

The (M, x) -extrapolation is

$$\text{Ext}_x^M(C) = (C \cap (x \leq M)) \cup \text{Cyl}_x(C \cap (x > M)) \cap (x > M).$$

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Generalized to (M, X) -extrapolation by applying to all clocks.

Integer reachability synthesis

Algorithm IEF(\mathcal{A}, G)

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 Pick a symbolic state (l, C) from the waiting list

 if $l \in G$ then $K \leftarrow K \vee IH(C) \downarrow_P$

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 then do not explore further this branch

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Integer complete reachability synthesis RIEF

Algorithm RIEF(\mathcal{A}, G)

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Pick a symbolic state (l, C) from the waiting list

if $l \in G$ then $K \leftarrow K \vee (l, C) \downarrow_P$

else if $(l, \text{IH}(\text{Ext}_X^M(C))) = (l', \text{IH}(\text{Ext}_X^M(C')))$,

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else store $(l, \text{IH}(\text{Ext}_X^M(C)))$ and add its successors to the waiting list

return K

Termination of RIEF

Theorem

For any PTA \mathcal{A} with bounded parameters, the computation of $\text{RIEF}(\mathcal{A}, G)$ terminates.

Proof (hint).

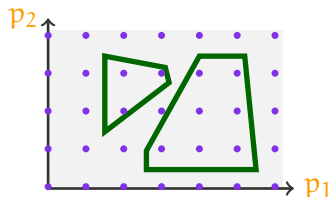
From the finiteness of the number of integer hulls of (M, X) -extrapolations of possible states. □

Characterization of RIEF

Theorem

Given a PTA \mathcal{A} with bounded parameters, $\text{RIEF}(\mathcal{A}, G)$ contains

- 1 no valuation that is not a solution of $\text{EF}(\mathcal{A}, G)$ [correctness]

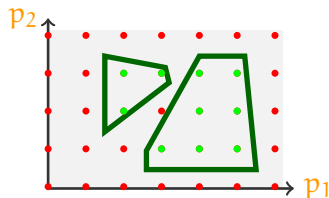


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Given a PTA \mathcal{A} with bounded parameters, $\text{RIEF}(\mathcal{A}, G)$ contains

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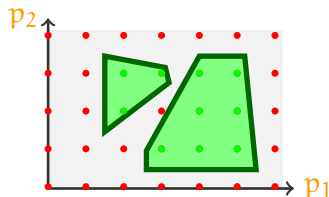


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- 1 no valuation that is not a solution of $\text{EF}(\mathcal{A}, G)$ [correctness]
- 2 all the integer parameter valuations solution of EF
[integer-completeness]
- 3 all the rational valuations in the parametric zones computed
by the symbolic exploration [?]



Unavoidability

Algorithm RIAF computing parameter valuations such that **a set of locations is unavoidable**

Similar principle and similar results

(see paper)

Outline

- 1 Preliminaries
- 2 Previous Works on Parameter Synthesis
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ROMÉO

Model checker for **parametric time Petri nets** and PTA [[Lime et al., 2009](#)]

Uses the Parma Polyhedra Library (PPL) for operations on polyhedra [[Bagnara et al., 2008](#)]

Available in the **open source** CeCILL license

www.ROMEO.xxx

Case study: scheduling example

Three tasks τ_1, τ_2, τ_3 scheduled using static priorities ($\tau_1 > \tau_2 > \tau_3$) in a non-preemptive manner [Jovanović et al., 2015]

Task τ_1 : periodic with period a and a non-deterministic duration in $[10, b]$

Task τ_2 : minimal activation time of $2a$ and a non-deterministic duration in $[18, 28]$

Task τ_3 : periodic with period $3a$ and a non-deterministic duration in $[20, 28]$.

Each task: deadline equal to its period

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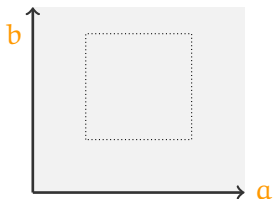
Task τ_3 : periodic with period $3a$ and a non-deterministic duration in $[20, 28]$.

Each task: deadline equal to its period

Goal: synthesize parameter valuations ensuring that the system does not reach a deadline violation.

Experiments

Bounded parameters: $a \in [0, 50]$ and $b \in [0, 50]$

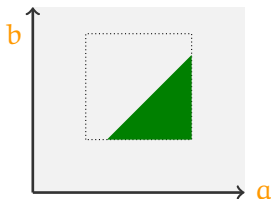


Algorithm	Result	Time
IEF	discrete	7.4 s
RIEF	dense	12.7 s

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Bounded parameters: $a \in [0, 50]$ and $b \in [0, 50]$

Result obtained by IEF: $a \geq 34$, $b \geq 10$, $a - b \geq 24$



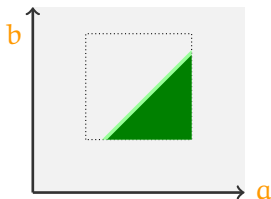
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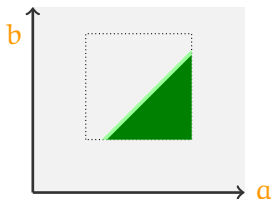
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- 😊 Slightly better result by RIEF
- 😞 Longer computation time (IH is expensive)
- 😊 Most important: RIEF is dense

Outline

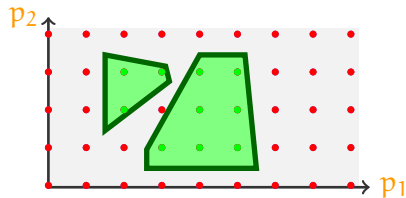
- 1 Preliminaries
- 2 Previous Works on Parameter Synthesis
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Summary

- Two synthesis algorithms for PTA with guaranteed termination and dense result
 - Dense valuations are important for **robustness**
- First terminating algorithms over dense valuations with guarantee on the results

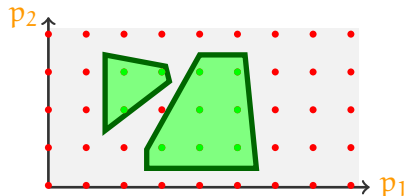
Perspectives

- Exact characterization of the result of RIEF and RIAF
 - What part of the result may be missing?



Perspectives

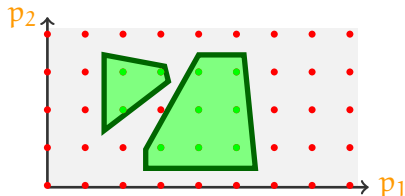
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- Extension of this principle to further algorithms
 - **Inverse method** (trace or language preservation) [A., Chatain, Encrenaz, Fribourg, 2009] and implementation in IMITATOR

Perspectives

- Exact characterization of the result of RIEF and RIAF
 - What part of the result may be missing?



- Extension of this principle to further algorithms
 - **Inverse method** (trace or language preservation) [A., Chatain, Encrenaz, Fribourg, 2009] and implementation in IMITATOR
- Use multi-core processors
 - E.g., some cores to compute successor states, and some to check the equality of integer hulls

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